1 Question 1 (TMJC 2020 Promos Q8)

The plane π contains the point A with coordinates (-2,1,4) and the line with equation

$$\mathbf{r} = \begin{pmatrix} 0\\3\\2 \end{pmatrix} + \lambda \begin{pmatrix} -2\\0\\1 \end{pmatrix}, \text{ where } \lambda \text{ is a parameter.}$$

- (i) Show that the cartesian equation of π is x + y + 2z = 7. [2]
- Let L be the set of lines such that the equation of any line l_a in L is given by

$$\mathbf{r} = \begin{pmatrix} -2a-2\\1\\4a+2 \end{pmatrix} + \mu \begin{pmatrix} -4-a\\1\\2a+3 \end{pmatrix}, \text{ where } \mu \text{ is a parameter and } a \text{ is a real constant.}$$

(ii) Verify that the point B with coordinates (6, -1, -4) lies on any line l_a in L. [2]

The equation of a particular line l_c in L is given by $\mathbf{r} = \begin{pmatrix} -2c-2\\1\\4c+2 \end{pmatrix} + \mu \begin{pmatrix} -4-c\\1\\2c+3 \end{pmatrix}$,

where μ is a parameter and c is a real constant. It is given that l_c is parallel to π .

- (iii) Show that c = -1. [1]
- (iv) Find the exact distance between l_c and π . [2]
- (v) Point F is the foot of perpendicular from B(6, -1, -4) to π and point C is on l_c . Given that the area of triangle *BCF* is $\frac{\sqrt{66}}{4}$ units², find possible position vectors of C. [5]

2 Question 2 (RI 2020 Promos Q2)

2 Referred to an origin *O*, points *A* and *B* have position vectors given respectively by $\mathbf{i} + 4\mathbf{j} + 8\mathbf{k}$ and $6\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}$. The point *P* on *AB* is such that $AP : PB = 1 - \lambda : \lambda$.

(i) Show that the exact area of triangle *OAB* is
$$\frac{5}{2}\sqrt{101}$$
. [1]

(ii) Find the exact value of
$$\lambda$$
 for which *OP* is perpendicular to *AB*. [3]

(iii) Find the exact value of λ for which angles *AOP* and *POB* are equal. [3]

3 Question 3 (TJC 2020 Promos Q9)

The points A, B and C lie on the circumference of a circle with center O and diameter AC. It is given that $\overrightarrow{OA} = \mathbf{a}$ and $\overrightarrow{OB} = \mathbf{b}$.

(i) Find \overline{BC} in terms of **a** and **b**. Hence show that AB is perpendicular to BC. [3]

The point *D* is on *BC* such that BD: DC = 3:2.

- (ii) Show that the area of triangle *OCD* can be written as $k |\mathbf{a} \times \mathbf{b}|$ where k is a real constant to be found. [3]
- (iii) Given that angle $AOB = 120^{\circ}$, find \overrightarrow{ON} in terms of **a** where N is the foot of perpendicular of D to AC. [4]

4 Question 4 (TJC 2020 Promos Q10)

Points *A* and *B* have coordinates (1,2,1) and (1,-5,2) respectively. The line *BC* has equation $\mathbf{r} = \begin{pmatrix} 1 \\ -5 \\ 2 \end{pmatrix} + \lambda \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}, \lambda \in \mathbb{R}.$

(i) Given that AB = AC, show that the coordinates of point C is (-3, -3, 4). [3]

(ii) Find the cosine of angle BAC and hence find the exact area of triangle ABC. [4]

(iii) Plane p is parallel to plane ABC and it is $\sqrt{\frac{11}{6}}$ units from plane ABC. Find the possible equations of p. [4]

(iv) Point D lies on p. Deduce the exact volume of the tetrahedron ABCD. [2]

[The volume of a tetrahedron of base area A and height h is given by $V = \frac{1}{3}Ah$.]

5 Question 5 (RI 2020 Promos Q9)

The plane p passes through the points with coordinates (2, 2, 4), (0, 6, 8) and (-2, -2, -3). (i) Find a cartesian equation of p. [4]

The line *l* has equation x-4=4-y, z=9.

(ii) Show that the coordinates of the point of intersection of l and p is (2, 6, 9). [2]

(iii) Find an equation of the line which is a reflection of
$$l$$
 in p . [6]

6 Question 6 (NJC 2020 Promos Q8)

Points *A*, *B* and *C* are non-collinear and origin *O* is not on the plane *ABC*. Point *P* has position vector given by $\overrightarrow{OP} = \lambda \overrightarrow{OA} + \mu \overrightarrow{OB} + (1 - \lambda - \mu) \overrightarrow{OC}$, where $\lambda, \mu \in \mathbb{R}$.

(i) Prove that *P* lies in the plane *ABC*. [2] It is now given that $\overrightarrow{OA} = \mathbf{i} + \mathbf{j} + \mathbf{k}$, $\overrightarrow{OB} = 2\mathbf{i} + 2\mathbf{j} + 4\mathbf{k}$ and $\overrightarrow{OC} = -2\mathbf{i} + \mathbf{k}$. Furthermore, *P* is

It is now given that $OA = \mathbf{1} + \mathbf{j} + \mathbf{k}$, $OB = 2\mathbf{i} + 2\mathbf{j} + 4\mathbf{k}$ and $OC = -2\mathbf{i} + \mathbf{k}$. Furthermore, *P* is the point of reflection of *B* in the line passing through *A* and *C*.

[5]

(ii) Find the value of λ and of μ .

7 Question 7 (NJC 2020 Promos Q7)

Referred to the origin, points A and B have non-zero position vectors **a** and **b** respectively.

(i) Show that
$$(\mathbf{a}+\mathbf{b})\times(\mathbf{a}-\mathbf{b})=-2(\mathbf{a}\times\mathbf{b}).$$
 [2]

- It is given that $|\mathbf{b}| = 2|\mathbf{a}|$.
- (ii) Find the maximum value of $|(\mathbf{a} + \mathbf{b}) \times (\mathbf{a} \mathbf{b})|$ in terms of $|\mathbf{a}|$. [3]

It is further given that A is a fixed point on the x-axis and B is a variable point on the xz-plane.

(iii) Given that the value of $|(\mathbf{a}+\mathbf{b})\times(\mathbf{a}-\mathbf{b})|$ is maximum, write down all possible expressions for $(\mathbf{a}+\mathbf{b})\times(\mathbf{a}-\mathbf{b})$ in terms of $|\mathbf{a}|$. [2]

8 Question 8 (EJC 2020 Promos Q12)

Stereophotogrammetry is a method of determining coordinates of points in the three-dimensional (3-D) replication of physical scenes. It relies on using multiple images taken by digital cameras from different positions.

In a simplistic model for this process, the camera sensors are represented by planes with finite size. A *ray of sight* for a particular point in the physical scene is defined as the line passing through its image point on the camera sensor and the focal point of the camera. The 3-D coordinates of a particular point is the intersection of the rays of sight from the different cameras.

For a particular set up, Camera 1 has focal point, F_1 at (20, 5, 10) and Camera 2 has focal point, F_2 at (-20, 5, 10). The image point of a point A, the highest tip of a flag pole, on Camera 1 is $A_1\left(\frac{61}{3}, 0, \frac{28}{3}\right)$, and the image point of A on Camera 2 is $A_2\left(-\frac{67}{3}, 0, \frac{28}{3}\right)$.

(i) Find the vector equations of l_1 and l_2 , the rays of sight for point A from the Cameras 1 and 2 respectively, and hence find the coordinates of point A. [4]

The base of the flag pole is known to be on the plane P that contains the point D(75, 90, -50) and the

line *L* with equation
$$\mathbf{r} = \begin{pmatrix} 23 \\ 90 \\ -46 \end{pmatrix} + s \begin{pmatrix} -1 \\ 6 \\ 1 \end{pmatrix}, s \in \mathbb{R}$$
.

(ii) Show that the vector equation of the plane P is $\mathbf{r} \cdot \begin{pmatrix} 1 \\ -2 \\ 13 \end{pmatrix} = -755$. [3]

The flag pole was erected perpendicular to the base plane *P*.

(iii) Find the coordinates of the point *B*, the base of the flag pole. [3]

[2]

- (iv) Hence or otherwise, find the length of the flag pole.
- (v) Given that the horizontal plane in this model is the *x-y* plane, find the angle of incline for the plane *P* from the horizontal plane.

9 Question 9 (EJC 2020 Promos Q5)

(a) The variable vector **u** satisfies the following equations:

$$\mathbf{u} \cdot \begin{pmatrix} 4\\1\\-2 \end{pmatrix} = -6 \text{ and}$$
$$\mathbf{u} \times \begin{pmatrix} 1\\2\\3 \end{pmatrix} = k \begin{pmatrix} 1\\-2\\1 \end{pmatrix}, \text{ for } k \in \mathbb{R}, k \neq 0.$$
(i) Explain why $\mathbf{u} \cdot \begin{pmatrix} 1\\-2\\1 \end{pmatrix} = 0.$ [1]

- (ii) Hence or otherwise, find the set of vectors **u** and describe this set geometrically. [3]
- (b) The points A, B and C have distinct non-zero position vectors a, b and c respectively and the vectors satisfy the equation c = λa + (1 − λ)b where λ ∈ ℝ, λ ≠ 0, λ ≠ 1. Prove that the points A, B and C are collinear.
- (c) Given that the point *P* has a non-zero position vector **p** and that the plane Π has equation $\mathbf{r} \cdot \mathbf{n} = 0$, where **n** is a unit vector, state the geometrical meaning of $|\mathbf{p} \cdot \mathbf{n}|$ in relation to the point *P* and the plane Π . [1]

10 Answers

1. (iv)
$$\frac{5\sqrt{6}}{3}$$
 units.
(v) $\overrightarrow{OC} = \frac{1}{10} \begin{pmatrix} 51\\-7\\-37 \end{pmatrix}$ or $\frac{1}{10} \begin{pmatrix} 69\\-13\\-43 \end{pmatrix}$.
2. (ii) $\lambda = \frac{11}{54}$.
(iii) $\lambda = \frac{7}{16}$.
3. (i) $\overrightarrow{BC} = -\mathbf{a} - \mathbf{b}$.
(ii) $k = \frac{1}{5}$.
(iii) $\overrightarrow{ON} = -\frac{4}{5}\mathbf{a}$.
4. (ii) $\cos(\angle BAC) = \frac{38}{50}$.
Area $= 2\sqrt{66}$ units²
(iii) $\mathbf{r} \cdot \begin{pmatrix} 4\\1\\7 \end{pmatrix} = 24$ or $\mathbf{r} \cdot \begin{pmatrix} 4\\1\\7 \end{pmatrix} = 2$.
(iv) $\frac{22}{3}$ units³.
5. (i) $2x + 5y - 4z = -2$.
(ii) $2x + 5y - 4z = -2$.
(iii) $\mathbf{r} = \begin{pmatrix} 2\\6\\9 \end{pmatrix} + \lambda \begin{pmatrix} 19\\-5\\-8 \end{pmatrix}, \lambda \in \mathbb{R}$.
6. $\lambda = 2.8, \mu = -1$.
7. $4 |\mathbf{a}|^2$.
8. (i) $A(15, 80, 20)$.
(iii) $B(10, 90, -45)$.
(iv) 66.0 units.
(v) 9.8° .

9. (iii) It is the perpendicular distance from point P to the plane $\Pi.$